





**Overview** 

## **Soft starters**



### Self-learning, intelligent diagnostics and easy to use



# Motor starting current 40% 50% 60% 75% 40% 50% 60% 75% DOL IE3 DOL IE2 RSBD RSBT RSBS HDMS RSGT RGTS



### New efficiency requirements for a.c induction motors (EU MEPS)

EU regulation EC 640/2009 related to minimum efficiency requirements for low voltage motors is being phased out and replaced by the EU 2019/1781.

The new regulation extends the requirement for motors with rated output power from  $0.75~\mathrm{kW}$  to  $1000~\mathrm{kW}$  to reach the higher efficiency class IE 3.

As of July 2023, motors with rated power of >75 kW and <200 kW must even reach a the higher efficiency class of IE4.

### Challenges caused by high efficiency motors

High efficiency motors are designed to reduce losses during motor operation by reducing rotor resistance. As a consequence there is a considerable increase in the locked rotor current. Whereas starting an IE2 motor via direct on line (DOL) results in a starting current of about 6 times the motor rated current, with IE3 motors starting current can be as high as 10 times. Such levels of starting current may cause increased machine stoppages due to tripping of protection circuits, oversizing of cables and fuses as well as disturbance on the voltage network.

### Minimising motor starting currents with soft starters

Carlo Gavazzi Soft Starters are already compatible with IE3 motors and can provide a typical 50% reduction with respect to a direct on line (DOL) start. A lower starting current avoids nuisance trips of prototection devices and reduces all the mechanical shocks experienced during motor starts. All this results in less machine stoppages and a longer lifetime for your motors.

### Unique benefits of Carlo Gavazzi Soft Starters



### **Self-learning**

Soft Starters integrate intelligent algorithms that adapt to the load requirements at every single start. As motors get old and/or the load requires

more torque during start, the soft starter automatically adjusts its internal parameters to keep your motors running.



### **Current balancing**

In the case of the two-phase controlled soft starters (RSGD, RSBD) the current imbalance is minimised to avoid nuisance tripping of protection devices.



### Fewer user adjustments

Thanks to the self-learning algorithm, our soft starters require minimal user adjustments.

This results in quicker commissioning and avoids

field tampering.



### Real-time diagnostics

Our soft starters continuously deliver data via Modbus. The data related to the motor energy consumption, running hours as well as the soft

starter status can be used to diagnose malfunctions as well as quicker troubleshooting.



### **Energy saving**

The soft starters are internally bypassed thereby reducing heat dissipation within the electrical panel.



### More protection for your motors

By integrating additional monitoring functions, the soft starters can detect abnormal operating conditions to protect your motors.



### Specification tables

				Rated current											
Applications	Supply	Series	Voltage Range	12	16	25	32	37	45	55	70	85	90	95	100
General AC motors	1-phase	RGTS	110 - 230 VAC	•	•	•									
	3-phase	RSGD	220 - 600 VAC	•	•	•	•		•	•	•	•			•
Scroll compressors	1-phase –	HDMS	110 - 230 VAC	•		•	•	•							
		RSBS	230 VAC				•								
	RSBD 3-phase	DCDD	220 - 400 VAC	•	•	•	•	•	•						
		K2RD	220 - 600 VAC							•	•			•	
		DCDT	220 - 400 VAC		•	•	•								
		K2R1	220 - 480 VAC							•	•			•	
Pumps and ventilators	3-phase	RSGT	220 - 600 VAC	•	•	•	•		•	•	•		•		

	1-phase 3-phase			hase			
	RGTS	HDMS	RSBS	RSGD	RSGT	RSBD	RSBT
Self-learning		•		•	▼	•	•
Current limit		•	▼	•	▼	▼	•
Current/voltage ramp	▼			•	▼		
Torque control				•	▼		
Controlled phases	1	1	1	2	3	2	3
Internal bypass		•	▼	•	▼	▼	•
Modbus		0		0	0		0
NFC		•					
Fault indication		•	•	•	•	•	0
Top of ramp		•		•	•	•	0
Run status indication				0	0		
Wrong phase sequence				•	•	•	•
Over- and under- voltage		•	▼	•	▼	•	•
Phase loss (motor side)		•	▼	•	▼		
Locked rotor		•	▼	•	▼	•	•
Over-temperature		•	▼	•	▼	•	•
Motor overload		•		•	▼	•	▼
Supply voltage imbalance				•	▼	•	•
Shorted power unit		•	▼	•	▼		
Thermistor (PTC) input				0	0		
	Current limit Current/voltage ramp Torque control Controlled phases Internal bypass Modbus NFC Fault indication Top of ramp Run status indication Wrong phase sequence Over- and under- voltage Phase loss (motor side) Locked rotor Over-temperature Motor overload Supply voltage imbalance Shorted power unit	Self-learning Current limit Current/voltage ramp  Torque control Controlled phases Internal bypass Modbus NFC Fault indication Top of ramp Run status indication Wrong phase sequence Over- and under- voltage Phase loss (motor side) Locked rotor Over-temperature Motor overload Supply voltage imbalance Shorted power unit	RGTS HDMS  Self-learning  Current limit  Current/voltage ramp  Torque control  Controlled phases  I I I  Internal bypass  Modbus  NFC  Fault indication  Top of ramp  Run status indication  Wrong phase sequence  Over- and under- voltage  Phase loss (motor side)  Locked rotor  Over-temperature  Motor overload  Supply voltage imbalance  Shorted power unit	RGTS HDMS RSBS  Self-learning   Current limit   Current/voltage ramp   Torque control   Controlled phases   Internal bypass   Modbus   NFC   Fault indication   Top of ramp   Run status indication   Wrong phase sequence   Over- and under- voltage   Phase loss (motor side)   Locked rotor   Wotor overload   Supply voltage imbalance   Shorted power unit   ▼ ▼	RGTS         HDMS         RSBS         RSGD           Self-learning         V         V           Current limit         V         V           Current/voltage ramp         V         V           Torque control         V         V           Controlled phases         1         1         1         2           Internal bypass         V         V         V           Modbus         O         O         O           NFC         V         V         V           Fault indication         V         V         V           Top of ramp         V         V         V           Run status indication         O         O         O           Wrong phase sequence         V         V         V           Over- and under- voltage         V         V         V           Phase loss (motor side)         V         V         V           Locked rotor         V         V         V           Over-temperature         V         V         V           Motor overload         V         V         V           Shorted power unit         V         V         V	RGTS         HDMS         RSBS         RSGD         RSGT           Self-learning         Y         Y         Y           Current limit         Y         Y         Y           Current/voltage ramp         Y         Y         Y           Torque control         Y         Y         Y           Controlled phases         1         1         1         2         3           Internal bypass         Y         Y         Y         Y           Modbus         O         O         O         O           NFC         Y         Y         Y         Y           Fault indication         Y         Y         Y         Y           Run status indication         O         O         O         O           Wrong phase sequence         Y         Y         Y         Y           Over- and under- voltage         Y         Y         Y         Y           Phase loss (motor side)         Y         Y         Y         Y           Locked rotor         Y         Y         Y         Y           Over-temperature         Y         Y         Y         Y           Motor overload	RGTS         HDMS         RSBS         RSGD         RSBD           Self-learning         V         V         V         V           Current limit         V         V         V         V           Current/voltage ramp         V         V         V         V           Torque control         V         V         V         V           Controlled phases         1         1         1         2         3         2           Internal bypass         V         V         V         V         V         V           Modbus         O         O         O         O         O         O         O           NFC         V

AvailableOptional or available on specific models only



### **RSGT** - High performance general purpose soft starters

### **Features**

Operational voltage: 220 - 600 VAC
Rated operational current: 12 to 90 AAC

- Three phase controlled
- Hybrid switching higher efficiency during operation
- Built-in diagnostic functions including electronic motor overload protection (Class 10)
- Relay outputs for fault indication and top of ramp
- Number of starts/hr: 12
- Dry run protection function
- Optional Modbus interface
- Easy to configure: only 3 adjustments required
- Compact dimensions



To further minimise torque shocks on the motor shafts and couplings the RSGT automatically

detects when the motor is running at full speed. This functionality ensures that the internal bypass relays are only switched on when the motor current drops to a safe level thereby avoiding any electrical and mechanical surges during such a transition. Disturbances on the electrical network are eliminated and motor lifetime is prolonged.



### Reduces water hammering in water pumps

RSGT's self-learning algorithm is active at every pump start and also during pump stopping. At every start and stop, the soft starter monitors

variables such as voltage and current and automatically modifies its internal parameters to smoothen the ramp profile thereby eliminating pressure shocks.



### Protects your pumps under all conditions

Functionality of RSGT goes beyond soft starting. Through a set of smart monitoring functions, RSGT continuously checks a set of critical

variables to signal any abnormal conditions. Some of these functions include wrong phase sequence, current imbalance and electronic motor overload protection.



### Minimises electrical and mechanical stresses

The RSGT controls the current on all the 3 phases. This control method ensures best in class current reduction and also eliminates current imbalance.

The maximum current during start is limited to 3.5 times the full load current (FLC) setting. With a ramp-up setting range up to 20 sec, both low and medium inertia fans can be smoothly started with the RSGT.











	NAME OF TAXABLE PARTY.			
	RSGT 45 mm	RSGT 75 mm	RSGT 120 mm	
Housing (H x W x D)	Up to 16 A: 130 x 45 x 105 mm 25 A: 150 x 45 x 105 mm	180 x 75 x 221 mm	180 x 120 x 221 mm	
Starts per hour	12	12	12	
Controlled phases	3	3	3	
nternally bypassed	Yes	Yes	Yes	
Relay outputs	2	3	3	
PTC input	No	Yes	Yes	
ntegrated overload protection (Class 10)	Yes	Yes	Yes	
Approvals	CE - cULus Listed - EAC	CE - cULus Listed - EAC	CE - cULus Listed - EAC	
SELECTION GUIDE	RSGT XX YY ZZ V10 K	RSGT XX YY ZZ V11 J K	RSGT XX YY ZZ V111 K	
(V Oti  t	40 220 - 400 VAC - 50 / 60 Hz	40 220 - 400 VAC - 50 / 60 Hz	40 220 - 400 VAC - 50 / 60 Hz	
XX Operational voltage —	60 220 - 600 VAC - 50 / 60 Hz	60 220 - 600 VAC - 50 / 60 Hz	60 220 - 600 VAC - 50 / 60 Hz	
	12 AAC	32 AAC	70 AAC	
YY Rated current	16 AAC	45 AAC	90 AAC	
	25 AAC	55 AAC		
77 Control voltage [DCCT40]	FO 24 VAC / DC	FO 24 VAC / DC	FO 24 VAC / DC	
ZZ Control voltage [RSGT40]	EO 110 - 400 VAC	EO 110 - 400 VAC	EO 110 - 400 VAC	
ZZ Control & supply voltage [RSGT60] —	FF 24 VAC/DC	FF 24 VAC/DC	FF 24 VAC/DC	
ZZ Collifor & Supply Vollage [K30100]	GG 100 - 240 VAC	GG 100 - 240 VAC	GG 100 - 240 VAC	
Fan	without fan —	1 with fan	— with fan	
ruii	WIIIIOUI IUII	0 without fan		
K Modbus interface	Nil without Modbus RTU C Modbus RTU	C Modbus RTU	C Modbus RTU	

### **Soft starters**

### **RSGD - General purpose soft starters**

### **Features**

Operational voltage: 220 - 600 VAC
Rated operational current: 12 to 100 AAC

• Two-phase controlled

• Hybrid switching - higher efficiency during operation

• Current balancing for improved load stability at start/stop

• Condition monitoring through Modbus RTU port

• Electronic motor overload protection (Class 10)

• Fully configurable via Modbus

• Torque control during soft stop

• Easy to configure: only 3 adjustments required

Compact dimensions

### Adapts to load conditions to optimise motor starts

The RSGD uses a proprietary self-learning algorithm that adjusts the internal start

parameters according to the load requirements. Whether the load connected to the motor shaft is low torque or high inertia, the RSGD is able to adjust the parameters at every start resulting in smoother motor starts under any load condition.



### Improves load stability with current balancing

The RSGD minimises motor audible noise during starts by balancing the currents on the

motor phases. As a result the motor starts much smoother and voltage disturbances are also minimised reducing the possibility of trips on the fuses and circuit breakers.



### Monitors motor performance in real time

The integration of the serial communication allows the RSGD to exchange real-time data with the machine PLC. Data includes electrical

variables as well as fault indication.

Such data can be very useful during commissioning, during troubleshooting and preventive maintenance activities.



### Stops pumps smoothly with torque control

The RSGD uses torque control as the default soft stop. Torque control monitors both voltage and current to ensure that the motor performs a

constant deceleration. This advanced approach eliminates pressure shocks and avoids water hammering.







			•		
	RSGD 45mm V.200	RSGD 45mm V.210	RSGD 75mm		
Housing (H x W x D)	Up to 32 AAC : 106 x 45 x 125 mm 45 AAC: 130 x 45 x 125 mm 32 AAC to 45 AAC: 130 x 45 x 125 mm		45 / 55 / 70 / 85 AAC: 170 x 75 x 180 mm 100 AAC: 221 x 75 x 180 mm		
Starts per hour (@ rated conditions)	Up to 20 Up to 20		10		
Controlled phases	2	2			
Internally bypassed	Yes Yes		Yes		
Relay outputs	2 2		3		
PTC input	No	No	Yes		
Electronic motor overload protection (Class 10)	No	Yes	Yes		
Modbus RTU	No	No	Yes		
Approvals	CE - cULus listed - CCC - EAC	CE - cULus listed - CCC - EAC	CE - cULus listed - CCC - EAC		
SELECTION GUIDE	RSGD XX YY ZZ V K 200	RSGD XX YY ZZ V K 210	RSGD XX YY ZZ V X 31 J C		
VV Operational voltage	<b>40</b> 220 - 400 VAC 50 / 60 Hz	40 220 - 400 VAC 50 / 60 Hz	40 220 - 400 VAC 50 / 60 Hz		
XX Operational voltage	60 220 - 600 VAC 50 / 60 Hz	60 220 - 600 VAC 50 / 60 Hz	60 220 - 600 VAC 50 / 60 Hz		
	12 AAC	12 AAC	55 AAC		
	16 AAC	16 AAC	70 AAC		
YY Rated current	25 AAC	25 AAC	85 AAC		
	32 AAC	32 AAC	100 AAC		
	45 AAC	45 AAC			
77 Central valtage [DCCD40]	FO 24 VAC/DC	FO 24 VAC / DC	FO 24 VAC / DC		
ZZ Control voltage [RSGD40]	FO 110 - 400 VAC	FO 110 - 400 VAC	FO 110 - 400 VAC		
77 Central 9 cumply voltage [DCCD40]	FF 24 VAC/DC	FF 24 VAC/DC	FF 24 VAC/DC		
ZZ Control & supply voltage [RSGD <mark>60</mark> ]	<b>GG</b> 100 - 240 VAC	<b>GG</b> 100 - 240 VAC	<b>GG</b> 100 - 240 VAC		
K Heatsink ——	D No heatsink [12/16/25/32 AAC] models	D No heatsink [12 / 16 AAC] models	V Eutomal heateink		
N HEUISHIK	X External heatsink [45 AAC] models	X External heatsink [25/32/45 AAC] models	X External heatsink		
J Fan	without fan	without fan	1 with fan [100 AAC models only]		
J Full	WIIIIOUI IUII	WIIIIOUI IUII	0 without fan		

### **Soft starters**

### RGTS, RSBS, HDMS - 1 phase soft starters

### **Features**

Operational voltage: Up to 230 VAC
Rated operational current: 12 - 37 AAC

• RGTS: Fully solid state

• RSBS/HDMS: Hybrid switching - higher efficiency during operation

• HDMS: Condition monitoring through Modbus RTU port

• HDMS: Faster troubleshooting with NFC technology

• Easy to configure

• Compact dimensions



### A complete line of single phase soft starters

Carlo Gavazzi provides a wide range of single phase soft starters suitable for different motor types. The RGTS is suitable for permanent split capacitor

(PSC) motors such as centrifugal pumps and ventilators. The RSBS is suitable for capacitor start motors including CSIR and CSCR type motors typically used in refrigeration and heat pump applications. The HDMS is suitable for CSCR motors primarily scroll compressors and submersible pumps as well as PSC motors with a starting time up to 1 sec.



### **Quick commissioning**

HDMS and RSBS do not require any user adjustments. The control algorithm automatically adjusts the starting torque required by the compressor. This

results in a tamper-free design and faster commissioning. The RGTS is a more basic soft starter and requires user adjustment for initial torque and ramp-up time. In the case of the RGTS, the ramp-up time can be extended to 5 sec.



### Continuously adjusts to load requirements

Compressors starting conditions change with every start. Thanks to its advanced algorithm, the HDMS automatically adjusts its internal parameters at

every start to adjust to the variable starting conditions.



### Identify deviations in the compressor performance

Compressor malfunctions can be detected through monitoring of specific electrical variables. The

HDMS has a native Modbus RTU serial port for real-time data exchange with the PLC. Data such as current consumption and power factor can highlight problems on the compressor in real-time.







		and the second second			
	RGTS	RSBS Gen 3	HDMS		
Housing (H x W x D)	100.4 x 54 x 113 mm	81.4 x 135 x 70.6 mm	85.6 x 153 x 86.7 mm		
Starts per hour (@ rated conditions)	10	10	10		
Controlled phases	1	1	1		
Internally bypassed	No	Yes	Yes		
Relay outputs	0	1	2 (configurable)		
PTC input	No	No	Yes		
Electronic motor overload protection (Class 10)	No	No	Yes		
Modbus RTU	No	No	Yes		
Approvals	CE - cULus listed	CE - cULus listed - EAC	CE - cULus listed		
SELECTION GUIDE	RGTS XX YY ZZ VOO	RSBS XX YY ZZ V23 C KK HP	HDMS XX YY ZZ V 2 KK		
XX Operational voltage	<b>24</b> 100 - 240 VAC 50 / 60 Hz	23 230 VAC 50 / 60 Hz	23 110 - 230 VAC 50 / 60 Hz		
	12 AAC	32 AAC	12 AAC		
YY Rated current	16 AAC		25 AAC		
TT Kuleu collelli	25 AAC		32 AAC		
			37 AAC		
ZZ Control voltage		A2 230 VAC	GO 110 - 230 VAC		
ZZ Supply voltage	OF 24 VAC/DC OG 100 - 240 VAC	Internally supplied	Internally supplied		
		00 External start capacitor	20 Panel mount		
VV Versions		10 100 μF internal start capacitor	21 DIN rail mount		
KK Versions		17 170 µF internal start capacitor	20C Panel mount + Modbus		
		24 240 µF internal start capacitor	21C DIN rail mount + Modbus		



### Soft starters

### RSBD, RSBT - 3 phase scroll compressor soft starters

### **Features**

- Operational voltage: Up to 600 VAC
  Rated operational current: 12 95 AAC
- Patented self-learning algorithm
- Hybrid switching higher efficiency during operation
- Two- and three-phase controlled versions
- No user adjustments required
- Condition monitoring through Modbus RTU port
- Compact dimensions



### Plug and play soft starters

The RSBD and RSBT soft starters are designed specifically for OEMs. They do not require any user adjustments for an error-free and fast

installation.



### Optimised starts under all starting conditions

The self-learning algorithm is also implemented in both the RSBD and RSBT soft starters. This

functionality allows the soft starters to dynamically change the start-up parameters to provide the optimal torque to start the compressor even under high differential starting pressures.



### Specifcally designed for scroll compressors

The RSBD and RSBT soft starters are tailored for scroll compressor applications. The ramp-up

time is internally limited to a maximum of 1 second to comply with scroll compressor manufacturers recommendations. Built-in monitoring functions provide additional protection to the compressor in case of abnormal operating conditions.



### Minimise load vibrations and eliminate light flickering

Another essential benefit of the RSBD and RSBT soft starters is that of current reduction. With the

RSBD, typically the current reduction vs DOL is in the region of 40% and that of the RSBT can be up to 60%. The lower starting current results in lower voltage network disturbances and lower maintenance costs.









RSBD 45 mm	RSBD 75 mm	RSBT 45 mm	RSBT 120 mm
125 x 45 x 106 mm	170 x 75 x 150mm	V11: 125 x 45 x 81 mm V21/VC1:125 x 45 x 103.5 mm	170 x 120 x 150 mm
12	12	12	12
2	2	3	3
Yes	Yes	Yes	Yes
2	3	1 (Option)	2
No	No	No	No
) No	No	No	No
No	No	Option	Option
CE - cULus listed - EAC	CE - cULus listed - EAC	CE - cULus listed - CCC - EAC	CE - cULus listed - CCC - EAC
RSBD XX YY ZZ V61HP	RSBD XX YY ZZ V61HP	RSBT XX YY ZZ V KK HP	RSBT XX YY ZZ V K
<b>40</b> 220 - 400 VAC 50/60 Hz	40 220 - 400 VAC 50/60 Hz 60 220 - 600 VAC 50/60 Hz	<b>40</b> 220 - 400 VAC 50/60 Hz	<b>48</b> 220 - 480 VAC 50/60Hz
12 AAC	55 AAC	16 AAC	55 AAC
16 AAC	70 AAC	25 AAC	70 AAC
25 AAC	95 AAC	32 AAC	95 AAC
32 AAC			
37 AAC			
E 110 - 400 VAC	E 110 - 400 VAC	E 110 - 400 VAC	C 24 VAC/DC
F 24 VAC / DC	F 24 VAC / DC	F 24 VAC / DC	& 110´- 400 VAC
	FF 24 VAC / DC (with 60 only)		
_	<b>GG</b> 100 - 240 VAC		
	_	11 No relay output	O Standard version
	_	21 Relay output — — C1 Modbus RTU	C Modbus RTU
	125 x 45 x 106 mm  12 2 Yes 2 No No No CE - cULus listed - EAC RSBD XX YY ZZ V61HP  40 220 - 400 VAC 50/60 Hz  12 AAC 16 AAC 25 AAC 37 AAC	125 x 45 x 106 mm  12  12  2  Yes  Yes  Yes  2  No  No  No  No  CE - cULus listed - EAC  RSBD XX YY ZZ V61HP  40 220 - 400 VAC 50/60 Hz  12 AAC  12 AAC  15 AAC  25 AAC  37 AAC  E 110 - 400 VAC  F 24 VAC / DC  12 D2  12 A12  12 C2  2 C2  2 A3  No  No  No  No  CE - cULus listed - EAC  CE - cULus listed - EAC  CE - cULus listed - EAC  AND  AND  AND  AND  AND  AND  AND  A	125 x 45 x 106 mm

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Energy to Components!



OVERVIEW SOFT STARTERS ENG 09/2021 Specifications are subject to change without notice. Illustrations are for example only.